

# QUANTUM MECHANICS

## Lecture 21

Dirac notation

Schrödinger equation in 3D

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D. J. Griffiths: paragraph 3.6, 4.1

In  $QM$ , very often, we have to evaluate **scalar products**  $\langle \mathbf{u} | \mathbf{v} \rangle$  between vectors of the Hilbert space, representing the physical states.

- 1 Dirac proposed to chop the bracket notation for the scalar product into two pieces:
  - the **bra**  $\langle u |$ ;
  - the **ket**  $|v \rangle$
- 2 Concerning the ket, the Dirac notation represents only a different way to write the vectors of  $\mathcal{H}$ :  $|v \rangle$  instead of  $\mathbf{v}$ .

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# Dirac notation

## 1 But what represents the *bra* $\langle u|$ ?

## 2 To answer, let us see what it does ...

It associates, in a linear way, a complex number to any vector of  $\mathcal{H}$ :

$$\langle u|(\alpha|v\rangle + \beta|w\rangle) = \alpha\langle u|v\rangle + \beta\langle u|w\rangle$$

## 3 It describes, therefore, a *linear function* defined from $\mathcal{H}$ to the complex field $\mathbb{C}$ .

## 4 The set of these linear functions forms a vector space.

$$(\alpha\langle u| + \beta\langle v|)|w\rangle = \alpha\langle u|w\rangle + \beta\langle v|w\rangle$$

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- 1 So, the bra  $\langle u|$  is an element of the dual space of  $\mathcal{H}$  (space that the mathematicians have shown to be isomorphic to  $\mathcal{H}$  itself).
- 2 According to this notation, for instance, the scalar product  $\langle u|\hat{Q}v \rangle$  becomes equal to the bra  $\langle u|$  applied to the vector  $\hat{Q}v$ . In other words, we have

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- 2 But this is not true !
- 3 As a matter of fact, with the Dirac notation, we have introduced **the bras  $\langle$  and kets  $|$  as separate entities from the bras  $\langle$  and kets  $|$**  and this allow us to define, now, some new interesting operators.

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- 1 Let  $|u\rangle$  be a normalized vector and let us define the following operator

$$\hat{P} = |u\rangle\langle u|$$

(be careful: this has nothing to do with  $\langle u|u\rangle$  which is a non-negative number !).

- 2 When we apply the operator  $\hat{P}$  to any vector  $|v\rangle$  of the Hilbert space, we obtain

$$\hat{P}|v\rangle \equiv |u\rangle\langle u|v\rangle = \langle u|v\rangle |u\rangle$$

which is the component of the vector  $|v\rangle$  *aligned* with the vector  $|u\rangle$ .

- 3 The operator  $\hat{P}$  is, in fact, the **projection operator** onto the one dimensional subspace of  $\mathcal{H}$ , generated by the vector  $|u\rangle$ .

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Let  $\{|e_n\rangle\}$  be a numerable, orthonormal basis of  $\mathcal{H}$ , made, for instance, by the eigenvectors of some observable  $\hat{Q}$ , although this is not essential: by hypothesis

$$\langle e_n | e_m \rangle = \delta_{nm}$$

It turns out that the operator

$$\sum_n |e_n\rangle \langle e_n|$$

is a ***representation of the identity***: we call it a **decomposition of the operator  $\mathbf{I}$** .

In fact, if  $|u\rangle$  is a generic vector, then we already know that

$$|u\rangle = \sum_n c_n |e_n\rangle \quad \text{where} \quad c_n = \langle e_n | u \rangle$$

In other words

$$\begin{aligned} |u\rangle &= \sum_n \langle e_n | u \rangle |e_n\rangle \equiv \\ &\equiv \sum_n |e_n\rangle \langle e_n | u \rangle \\ &\Leftrightarrow \sum_n |e_n\rangle \langle e_n| = I \end{aligned}$$

- 1 Similarly, if  $\{|e(s)\rangle\}$  is a Dirac orthonormalized "continuous" basis, such that

$$\langle e(s)|e(t)\rangle = \delta(s - t)$$

then

$$I = \int ds |e(s)\rangle \langle e(s)|$$

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- ② **The decomposition of the identity is nothing else than a direct manifestation of the completeness and orthonormality of the basis.**

- 1 Clearly, every orthonormal basis  $\{|e(s)\rangle\}$  defines its characteristic decomposition of the identity

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For instance, if we use the basis made by the normalized generalized eigenvectors

$$|x\rangle \equiv |e(x)\rangle$$

of the position operator  $\hat{x}$ , then the generic vector of the Hilbert space  $|\psi\rangle$  will be represented as

$$|\psi\rangle = \int dx |x\rangle \langle x|\psi\rangle = \int dx \psi(x) |x\rangle$$

where  $\psi(x) \equiv \langle x|\psi\rangle$  is the usual "old" wave function which, according to the generalized statistical interpretation, is such that  $|\psi(x)|^2$  gives the p.d.f. to measure, on the state  $|\psi\rangle$ , the particle position between  $x$  and  $x + dx$ .

- ① But if we use, instead, the generalized momentum eigenvectors  $|p\rangle \equiv |e(p)\rangle$ , then we can represent the same vector as

$$|\psi\rangle = \int dp |p\rangle \langle p|\psi\rangle = \int dp \phi(p) |p\rangle$$

where  $\phi(p) \equiv \langle p|\psi\rangle$  is now the momentum wave-function and  $|\phi(p)|^2$  gives the p.d.f. to measure, on the state  $|\psi\rangle$ , a momentum between  $p$  and  $p + dp$ .

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- 1 The generalization of the Schrödinger equation in three dimensions is quite straightforward.
- 2 The time-dependent Schrödinger equation says

$$i\hbar \frac{\partial \psi}{\partial t} = \hat{H} \psi$$

where, as already well known, the hamiltonian operator is obtained from the classical total energy

$$H = \frac{p^2}{2m} + V(\vec{r})$$

which, in three dimensions, becomes

$$\frac{1}{2m}(p_x^2 + p_y^2 + p_z^2) + V(\vec{r})$$

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Using the usual prescription

$$p_x \rightarrow -i\hbar \frac{\partial}{\partial x}; \quad p_y \rightarrow -i\hbar \frac{\partial}{\partial y}; \quad p_z \rightarrow -i\hbar \frac{\partial}{\partial z}$$

we obtain

$$i\hbar \frac{\partial \Psi}{\partial t} = -\frac{\hbar^2}{2m} \nabla^2 \Psi + V(\vec{r}) \Psi$$

where  $\nabla^2$  is the **Laplacian operator**

$$\nabla^2 \equiv \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$$

and the meaning of the w.f. is now that the probability of finding the particle in the volume  $dv = dx dy dz$  is  $|\Psi(\vec{r}, t)|^2$ , once the wave function  $\Psi$  has been normalized to the unity in the whole space.

- 1 In order to give the wave-function definition that we have done previously, we have implicitly assumed that the three position coordinates can be measured simultaneously, or, in other words, that the operators  $\hat{x}$ ,  $\hat{y}$ ,  $\hat{z}$  are compatible.
- 2 This is clearly true, because they are represented by the multiplication for  $x$ ,  $y$  and  $z$ , respectively, and the multiplication of real numbers **do** commute. So

$$[\hat{x}, \hat{y}] = [\hat{x}, \hat{z}] = [\hat{y}, \hat{z}] = 0$$

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- 1 Also the three momentum components represented by the operators  $-i\hbar\partial_x$ ,  $-i\hbar\partial_y$ ,  $-i\hbar\partial_z$  **do commute** and, therefore, they describe compatible observables.
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Concerning the compatibility of position and momentum components, from the definition of the respective operators, it turns out, instead, that **homologous components are incompatible** and we have

$$[x, p_x] = [y, p_y] = [z, p_z] = i\hbar$$

whereas non-homologous components are indeed compatible

$$[x, p_y] = [x, p_z] = 0$$

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- 1 But let us come back to the **Schrödinger equation in 3D**.
- 2 If the energy potential  $V = V(\vec{r})$  is time independent, similarly to the one-dimensional case, there will be a **complete set of stationary states**

$$\Psi(\vec{r}, t) = \psi(\vec{r}) e^{-iEt/\hbar}$$

where the functions  $\psi(\vec{r})$  satisfy the time independent Schrödinger equation, that now reads

$$-\frac{\hbar^2}{2m} \nabla^2 \psi(\vec{r}) + V(\vec{r}) \psi(\vec{r}) = E \psi(\vec{r})$$

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and the general solution of the time-dependent Schrödinger equation will be

$$\Psi(\vec{r}, t) = \sum_n c_n \Psi_n(\vec{r}, t) = \sum_n c_n \psi_n(\vec{r}) e^{-iE_n t/\hbar}$$

where the coefficients  $c_n$  are determined in the usual way, from the  $\Psi(\vec{r}, 0)$

$$c_n = \int d^3r \psi_n^*(\vec{r}) \Psi(\vec{r}, 0)$$

where the  $\psi_n(\vec{r})$  are the solutions of the time independent Schrödinger equation, or, in other words, the **eigenfunctions of the Hamiltonian operator**.